

INVARIANTS IN AFFINE DIFFERENTIAL GEOMETRY (*)

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SOMMARIO. - *In questo lavoro si ottengono soluzioni dell'equazione di Monge-Ampère $\det(\text{Hess } z) = 1$. Si da inoltre un risultato del tipo Theorema egregium.*

SUMMARY. - *In this paper one obtains solutions of the Monge-Ampère equation $\det(\text{Hess } z) = 1$. Furthermore one formulates a result of type Theorema egregium.*

Suppose A is the $(n+1)$ -dimensional real affine space with associated vector space V and denote by M an n -dimensional differentiable manifold without boundary.

A pair (M, x) where $x : M \rightarrow A$ is an immersion is called a *hypersurface of A* . Choosing a fixed origin in A we identify A with its vector space V .

A *relative normalization* of a hypersurface (M, x) is a mapping $y : M \rightarrow V$ such that in every point of M

- (i) the vectors y, x_1, \dots, x_n are linearly independent;
- (ii) the vector y_i is contained in the span of x_1, \dots, x_n for every $i = 1, 2, \dots, n$.

As usual an index denotes partial differentiation with respect to a local coordinate system on M .

The triple (M, x, y) is called a *relative normalized hypersurface*. Denote by V^* the dual vector space and by $\langle \cdot, \cdot \rangle : V^* \times V \rightarrow R$ the non-degenerate scalar product.

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Then the differentiable mapping $X : M \rightarrow V^*$ such that in every point of M

- (i) $\langle X, x_i \rangle = 0$ for every $i = 1, \dots, n$ and
- (ii) $\langle X, y \rangle = 1$

is called the induced *conormal* of the tangential plane. It is uniquely determined by the hypersurface (M, x, y) .

The immersion $x : M \rightarrow A$ is said to be *regular* when $\{X, X_1, \dots, X_n\}$ forms a basis of V^* .

A *metric* on M is induced from (M, x, y) by the formula

$$G_{ij} = -\langle X_i, x_j \rangle, \quad i, j = 1, 2, \dots, n.$$

G_{ij} is definite whenever $x : M \rightarrow A$ is non-degenerate.

The hypersurface (M, x, y) induces the *relative Weingarten tensor* B_{ij} by

$$B_{ij} = \langle X_i, y_j \rangle, \quad i, j = 1, 2, \dots, n;$$

the *affine mean curvature* H is the first curvature function, i.e.

$$H = \frac{1}{n} B_i^i.$$

A hypersurface (M, x, y) is called *affine maximal* if the affine mean curvature vanishes identically.

An affine maximal hypersurface is an *improper affine sphere* if the relative normalization is constant.

Suppose $|\cdot| : V^n \rightarrow R$ is a fixed determinant form. Define θ_{ij} , and g_{ij} , $i, j = 1, \dots, n$, by

$$\begin{aligned} \theta_{ij} &= |x_{ij}, x_1, \dots, x_n|, \\ g_{ij} &= |\text{Det}(\theta_{ij})|^{-1/(n+2)} \theta_{ij}. \end{aligned}$$

Then g_{ij} defines a definite tensor field on M which is by proper choice of orientation positive definite.

The Laplacian of (M, g_{ij}) induces a relative normalization y by

$$y = \frac{1}{n} \Delta x.$$

This normalization is called the *equiaffine normalization* of (M, x) .

The above introduction is given by Schneider in [SCHN]. In [SCHN] the Weingarten tensor differs by sign from the above definition.

A wide class of affine hypersurfaces is formed by affine maximal surfaces (cf. [CAL], [SCHI], [SCHN], [SI]).

Suppose Ω is a region in the plane and that an affine surface $\Sigma : \Omega \rightarrow A_3$ is given by a differentiable function $z : \Omega \rightarrow R$ as a graph over Ω

$$\Sigma(x, y) = \begin{bmatrix} x \\ y \\ z(x, y) \end{bmatrix}.$$

The determinant of the Hessian of z over Ω shall be denoted by d

$$(1) \quad d = \det(\text{Hess } z) = z_{xx}z_{yy} - z_{xy}^2.$$

The surface is an improper affine sphere if $z : \Omega \rightarrow R$ solves the Monge-Ampère equation

$$(2) \quad z_{xx}z_{yy} - z_{xy}^2 = 1.$$

The affine surface $\Sigma : \Omega \rightarrow A_3$ is an affine maximal surface if $z : \Omega \rightarrow A_3$ solves the Euler-Lagrange equation

$$\begin{aligned} & d\{z_{xx}d_{yy} + z_{yy}d_{xx} - 2z_{xy}d_{xy}\} = \\ (3) \quad & = \frac{7}{4}\{z_{xx}d_y^2 + z_{yy}d_x^2 - 2z_{xy}d_xd_y\}. \end{aligned}$$

A non-trivial solution of (2) is induced by the differential

$$(4) \quad dz = \text{tg } x \sqrt{\cos^2 x + y^2} dx + \text{arsh} \left[\frac{y}{\cos x} \right] dy.$$

This exact differential is defined in a region with $\cos x \neq 0$. Otherwise (4) solves the Monge-Ampère equation (2), i.e. the affine surface is an improper affine sphere.

It is convenient to introduce the positive function $\mu : \Omega \rightarrow \mathbb{R}$ and the dual field $W : \Omega \rightarrow V^*$

$$(5) \quad \mu := \frac{1}{4\sqrt{d}}, \quad W = \begin{bmatrix} -z_x \\ -z_y \\ 1 \end{bmatrix}.$$

Then we obtain

$$(6) \quad K = \mu \begin{bmatrix} -z_x \\ -z_y \\ 1 \end{bmatrix} = \mu W, \quad G = \text{Hess}(z) = \mu \begin{bmatrix} z_{xx} & z_{xy} \\ z_{xy} & z_{yy} \end{bmatrix},$$

where $K : \Omega \rightarrow V^*$ denotes the conormal of the tangential plane.

The support function $\sigma : \Omega \rightarrow \mathbb{R}$ with respect to the origin is given by

$$(7) \quad \sigma(x, y) = -\langle K(x, y), \Sigma(x, y) \rangle.$$

A well-known solution of (2) is given by

$$z = \frac{x^2 + y^2}{2}$$

and describes the elliptic paraboloid.

By (7) one has for its support function

$$(8) \quad \sigma = \frac{x^2 + y^2}{2} = z.$$

Another example of a solution of the Monge-Ampère equation (2) is given by

$$(9) \quad z = \frac{2}{3}(x^2 + y^2)^{3/2}.$$

Using (7) one gets for the induced support function

$$(10) \quad \sigma = \frac{1}{3}(x^2 + y^2)^{3/2} + (x^2 + y^2)^{1/2}.$$

Suppose $f : R^+ \rightarrow R$ is defined by the integral

$$(11) \quad f(r) = \int_0^r \sqrt{1 + \tau^2} \, d\tau,$$

and $z : R^2 \setminus \{0\} \rightarrow R$ is given by

$$(12) \quad z = f(r) \quad \text{with} \quad r^2 = x^2 + y^2.$$

Then z is a solution of the Monge-Ampère equation (2). By (7) one has for the induced support function

$$(13) \quad \sigma = -f(r) + r\sqrt{1 + r^2}.$$

In regions with sufficiently large r one has $f(r) \approx \frac{1}{2}r^2$. Thus by (13) $\sigma \approx f(r)$.

Like $z : \Omega \rightarrow R$ the determinant of the Hessian $d : \Omega \rightarrow R$ also induces an affine surface $\theta : \Omega \rightarrow A_3$

$$\theta(x, y) = \begin{bmatrix} x \\ y \\ d(x, y) \end{bmatrix}.$$

We consider here the elliptic case, i.e. $d : \Omega \rightarrow R$ is strictly positive and $\theta : \Omega \rightarrow A_3$ lies in the "upper" half plane.

For example consider the elliptic paraboloid. Then $d \equiv 1$, i.e. $\theta : \Omega \rightarrow A_3$ is a plane.

A solution of the Euler Lagrange equation (3) is given by

$$z(x, y) = -\frac{9}{2}x^{2/3} + \frac{y^2}{2}, \quad x > 0, \quad y \in R.$$

For this solution one gets

$$d = z_{xx}z_{yy} - z_{xy}^2 = x^{-4/3}.$$

Finally we give the following

THEOREM. *Suppose $x : M \rightarrow A_3$ is an affine surface with induced Berwald-Blaschke metric G such that the affine mean curvature vanishes and that (M, G) is a complete Riemannian space. Then the Pick invariant is not bounded from below by a positive constant.*

Proof. Because of the affine Theorema egregium $K = 2(J + H)$, where K denotes the Gauss curvature, J the Pick-invariant and H the affine mean curvature. As H vanishes the assertion follows from a theorem of Myers [MYE].

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